A satellite with blue solar panels and a central body is shown in orbit against a blue sky background.

# **Remote sensing image real-time processing for rapid disaster emergency response**

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A view of the Earth from space, showing the curvature of the planet, blue oceans, white clouds, and green landmasses.

# Outline



- 1、 Major requirements in disaster emergency response**
- 2、 Main technical challenges**
- 3、 Conclusions**

# 1、 Big spatio-temporal gap between decision maker and actual disaster information



2008 Wenchuan  
earthquake



2012 Zhaotong  
earthquake



2013 Yaan  
earthquake

The rapid data acquisition and real-time **processing** of spatio-temporal data in disaster emergency response **is seriously important**



# Sensor network is necessary for comprehensive disaster monitoring



InSAR



Optical



GNSS



UAV



Airborne



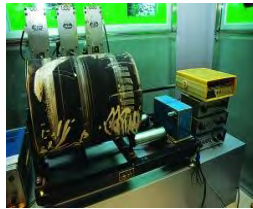
Airplane



GBR



Meteorological station



Seismic Thumper

**Space-based:** wide range, low time resolution

Hundreds of satellites

**Aerial-based :** high time and space resolution, limited coverage

Thousands of aircrafts

**Ground-based :** high mobility, limited coverage and manual intervention

Millions of ground sensors

**“Swimming in Sensors and Drowning in Data”**

—David Deptula, the U.S. air marshal

# Rich data, Little information, Poor knowledge



For the limitations of rapid data processing, satellite data can be processed in time for less than **10%**. How to timely, effectively and rationally integrate dispersed, massive and heterogeneous data is urgent and difficult problem



*“Ingesting all of the data the agency requires remains a major challenge, regardless of how omnipotent an organization is perceived to be. And **even once it is collected, analyzing it all in real-time is next to impossible.**”*

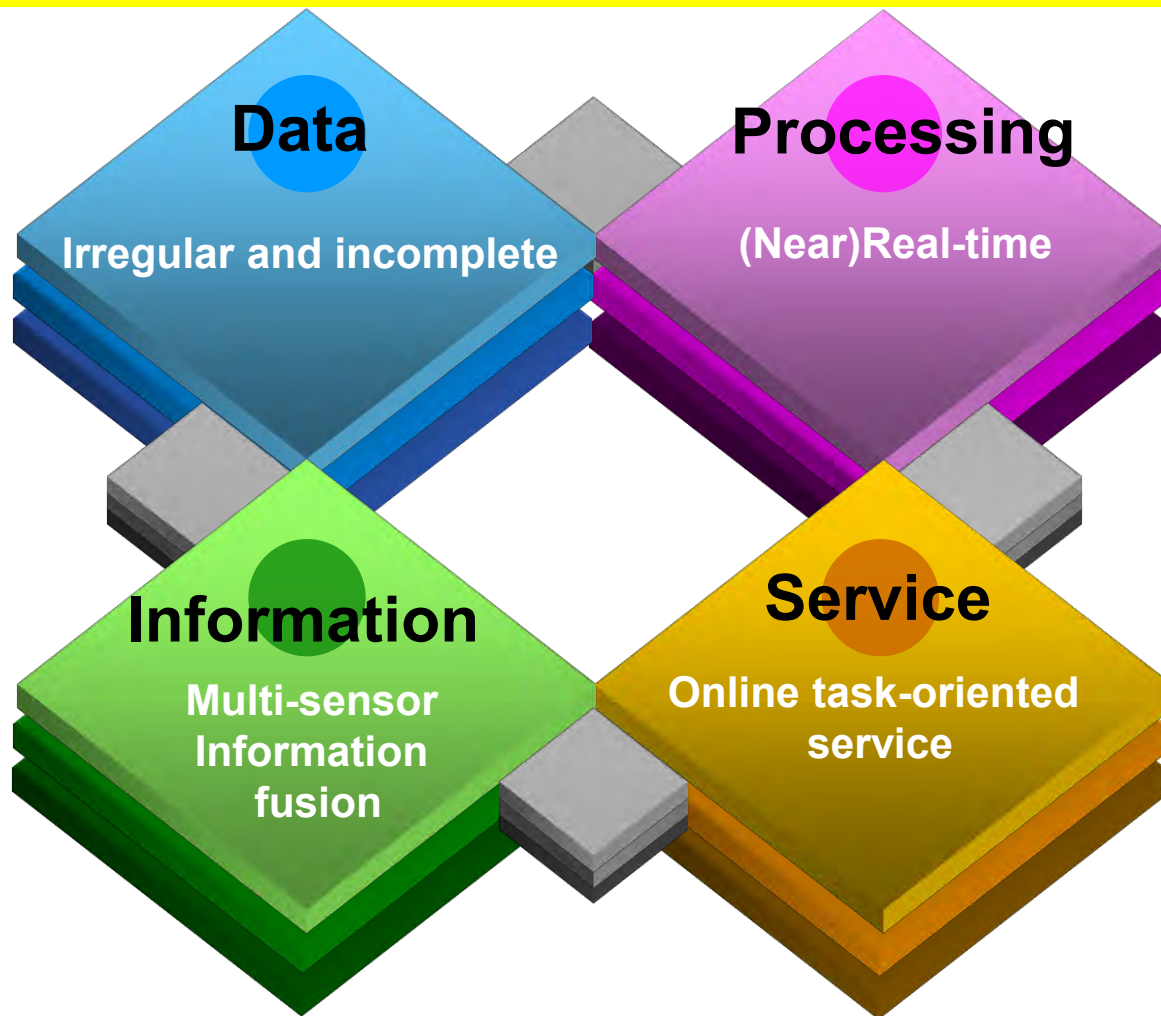
*“To watch all the video that currently moves across the Internet in one minute would take five years to watch. And we can’t ingest all that data at scale.”*

**—Meyerriecks**

25-Oct-13

the Director of Central Intelligence Agency's Directorate of Science and Technology team

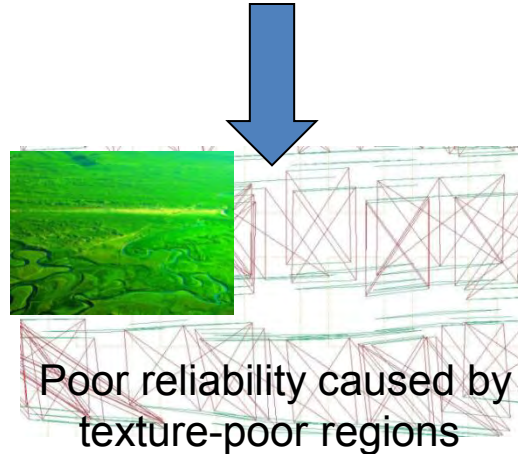
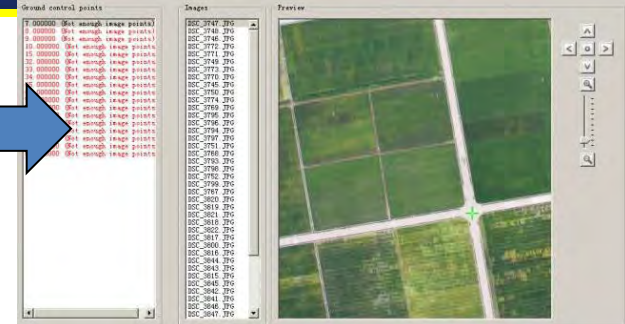
## 2、 Main technical challenges



**Core problem: Real-time continuous spatio-temporal  
Interpretation using discrete observation data**



# Challenge 1: Irregular and incomplete image data processing in emergency situations



Poor reliability caused by texture-poor regions



## Difficulties:

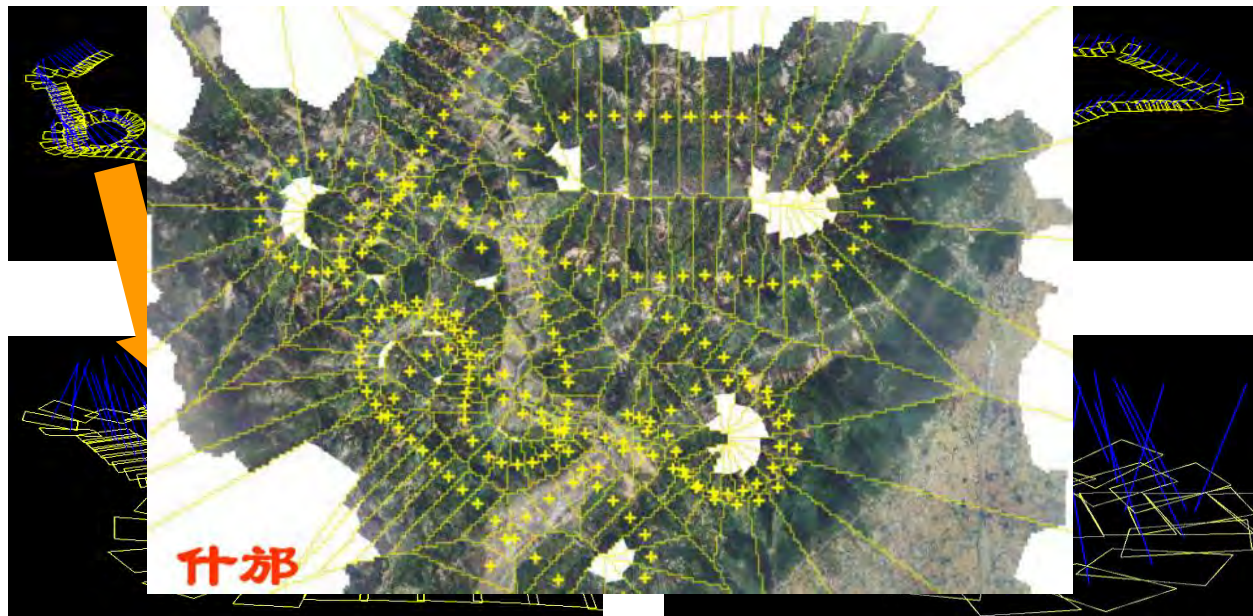
- Incomplete fundamental data
- No (little) control points
- Irregular, incomplete and non-canonical UAV data processing caused by pose information instable and data errors.

# Example 1: Irregular data processing



**Breakthrough** automatic image matching of unconventional aviation images in complex terrain and bad weather condition

**Solve** the problem of traditional operation mode's incapability of fast emergency response



## Simultaneous fly, view and imaging



# Example 2: Ortho-rectification with few or without control points



Connect Tags

输入路径	输入名称	输入类型	输出路径	输出名称
I:\tx\dim...	TSX1_SAR...	xml	D:\	TSX1_SAR...

RPC生成

Origin terra-SAR

Terra-SAR Orthorectified

Result

Origin SPOT5

SPOT5 Orthorectified Result

开始

基于拓展RPC模型卫星遥感影像几何纠正

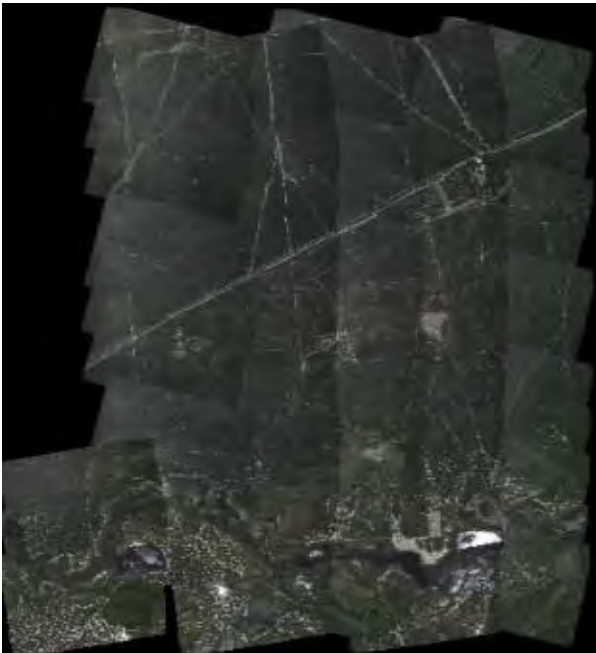
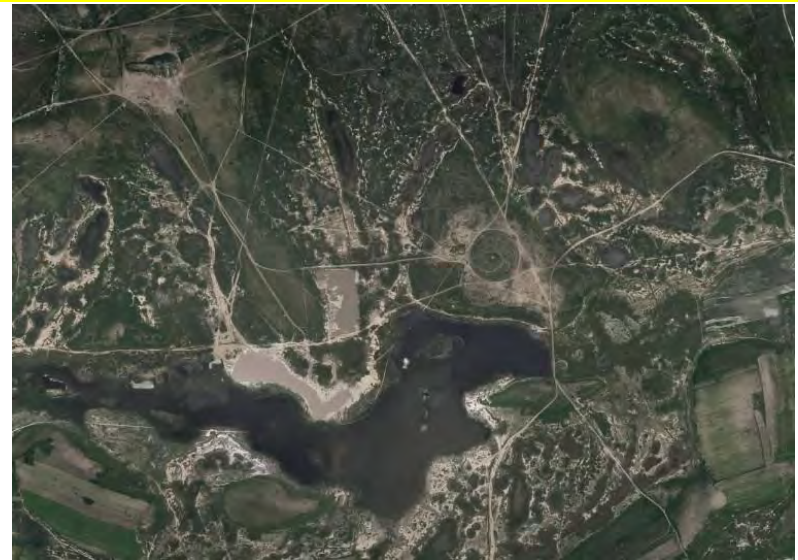
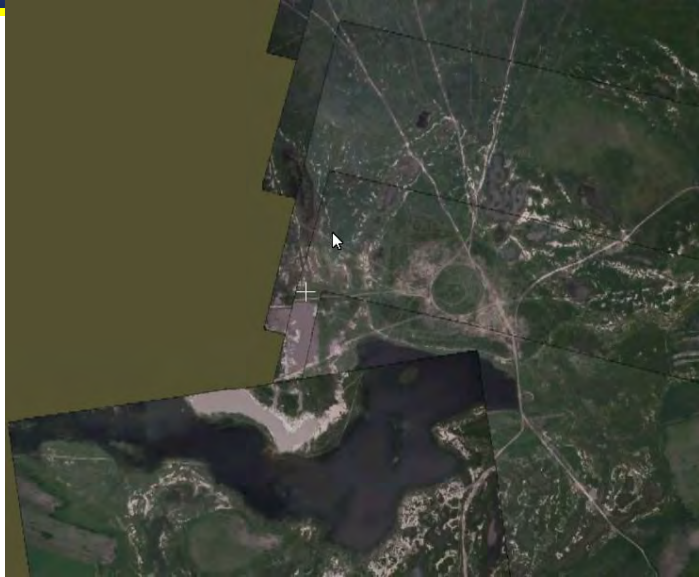
投影方式

	My	My	投影方式
32	-0.2237	2.4166	UTM Nort...
5	-1.8221	1.8310	UTM Nort...
38	5.2784	45.6957	UTM Nort...
1	-3.1741	3.4992	UTM Nort...
59	-1.2108	1.4327	UTM Nort...
72	-A 4846	9.4087	UTM Nort...

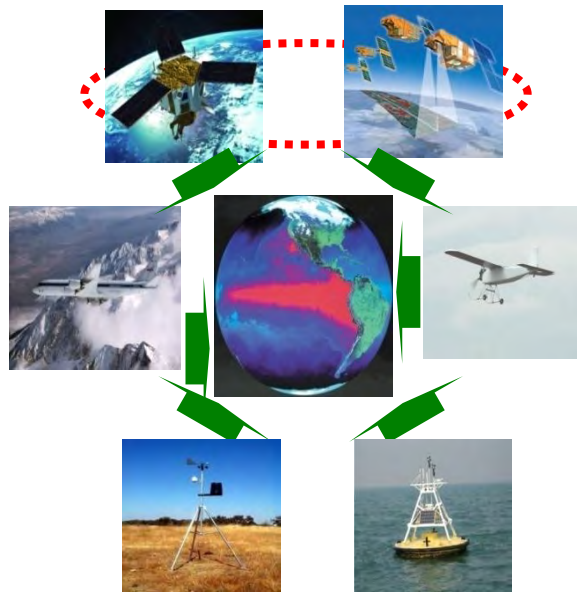
0.0000 (总计)0.0000 保存



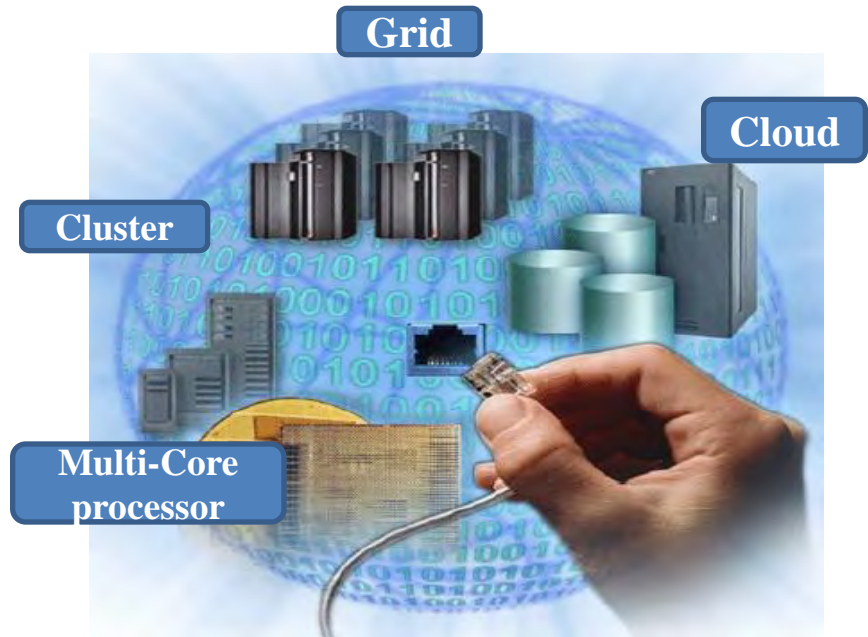
# Example 3: Incomplete data caused by instable small UAV



# Challenge 2: Real-time processing of integrated space/aerial/ground sensor data



**Real-time processing of integrated space/aerial/ground data is just the beginning**



**High-performance computing for Integrated hard/soft and big data**

**Difficulty: How to realize massive spatio-temporal data real-time high-performance computing?**



# Real-time processing is still a long way to go



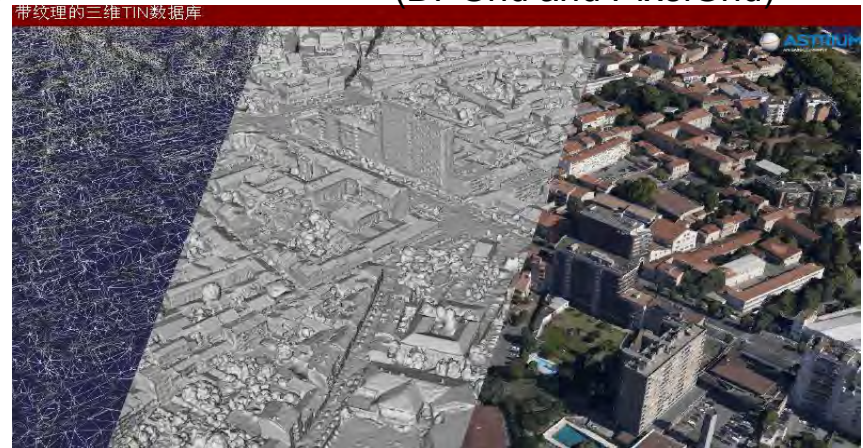
Pixel Factory of France  
(World-class remote sensing automatic processing system)



“Building Rome in a Day”



Pixel Factory of China  
(DPGrid and PixelGrid)

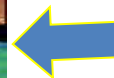
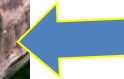
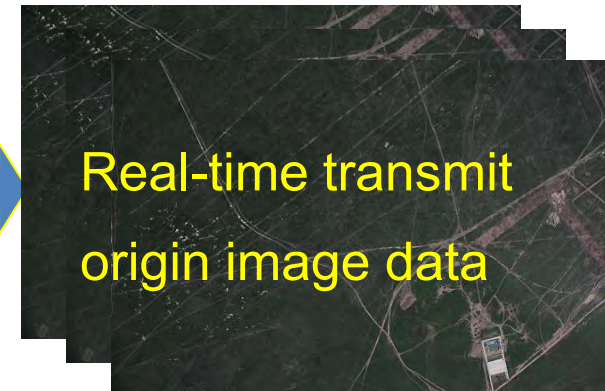
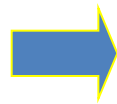


Street Factory's for 3D reconstruction  
(Paris reconstruction in 2 days, 83%, 30% overlapping)

**The batch processing techniques for satellite/aerial visible images has been very mature, and the 3D reconstruction of multi-angle camera images is gradually becoming practical.**

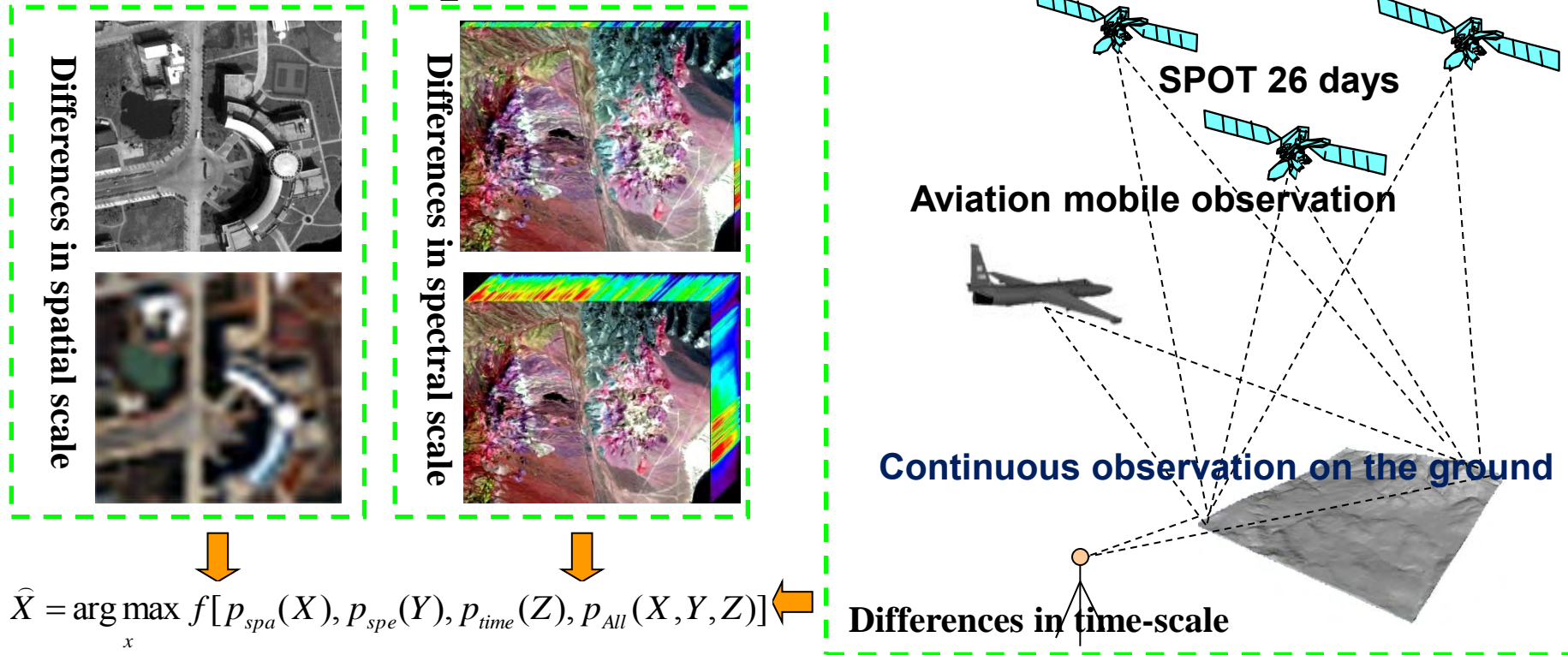


# Example : Real-time UAV image data products and change detection



# Challenge 3: Multi-sensor data assimilation and information collaborative computing

## Problem description:



**Difficulty: How to achieve assimilation and information fusion with multi-scale multi-temporal/spectral data?**



# Example 1: Oblique remote sensing image processing



Image Before Tsunami



控制点编辑

点号	基影像X
00061	914.00000...
00023	506.00000...



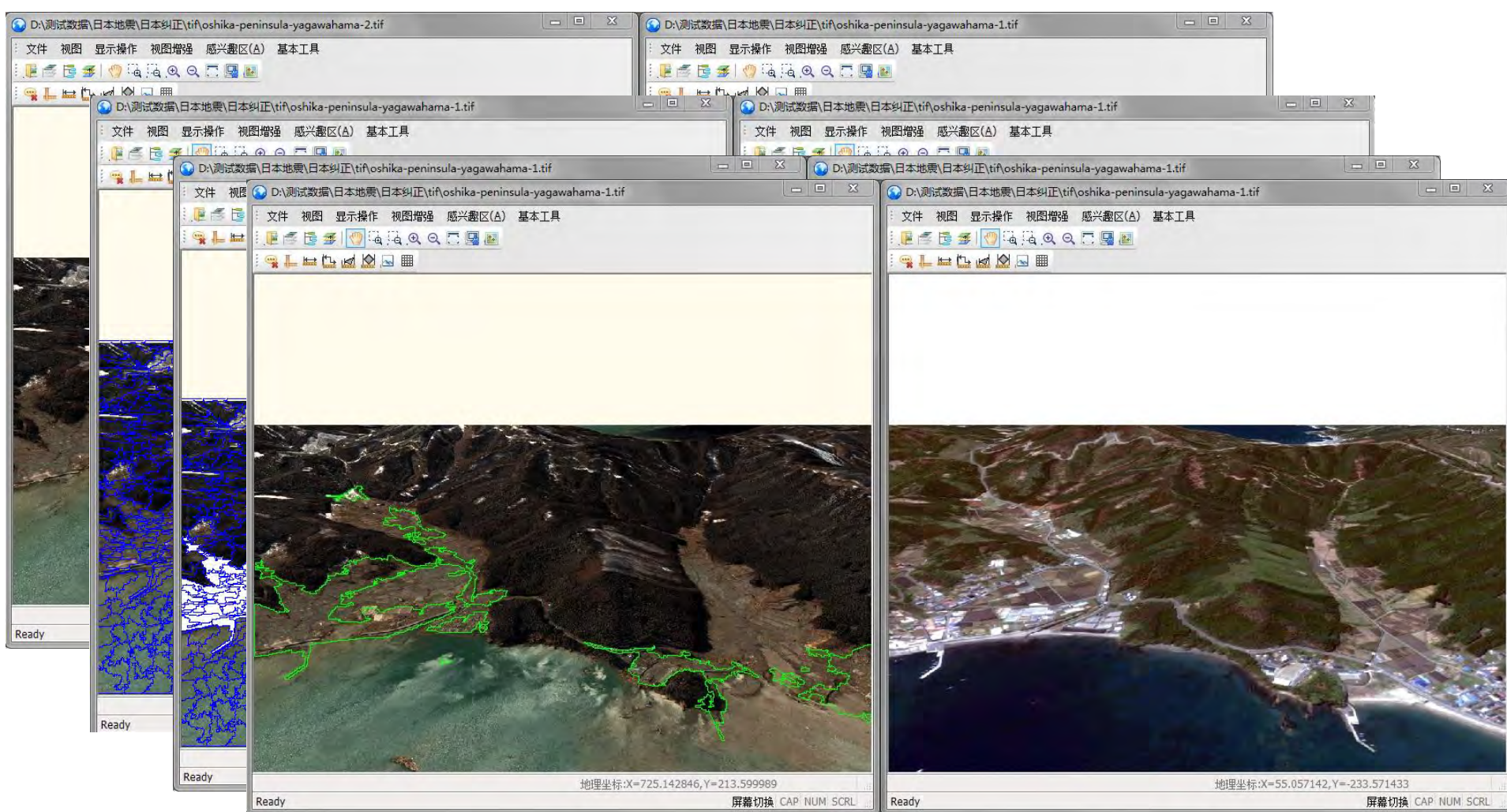
Registered Tsunami image



	中误差	总
512...	3.8813409...	总
172...	3.2266062...	总



# Building damage extraction based on object-level change detection

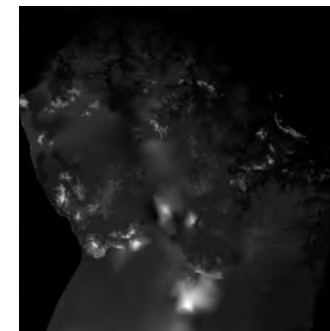
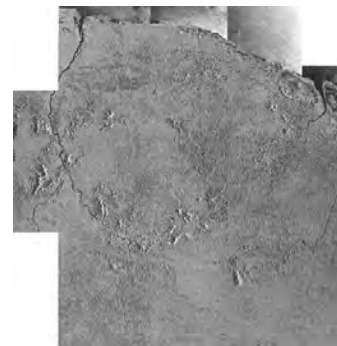


Object-oriented change detection results

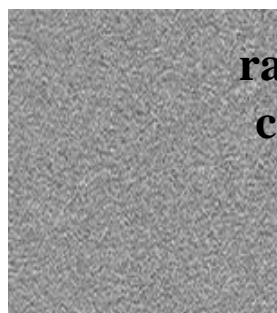
# Example 2: Optical & SAR image registration



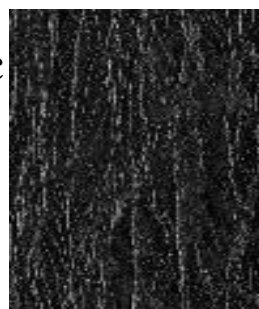
SAR images with same area and different side-looking



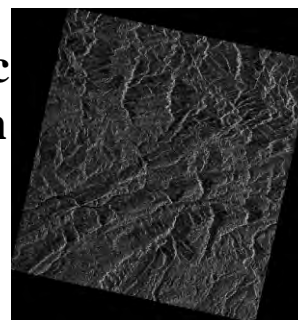
SAR (left) and optical (right) images with the same area



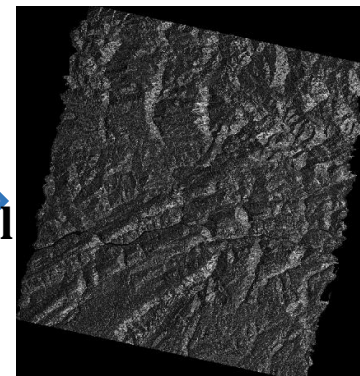
radiometric  
correction



Geometric  
correction



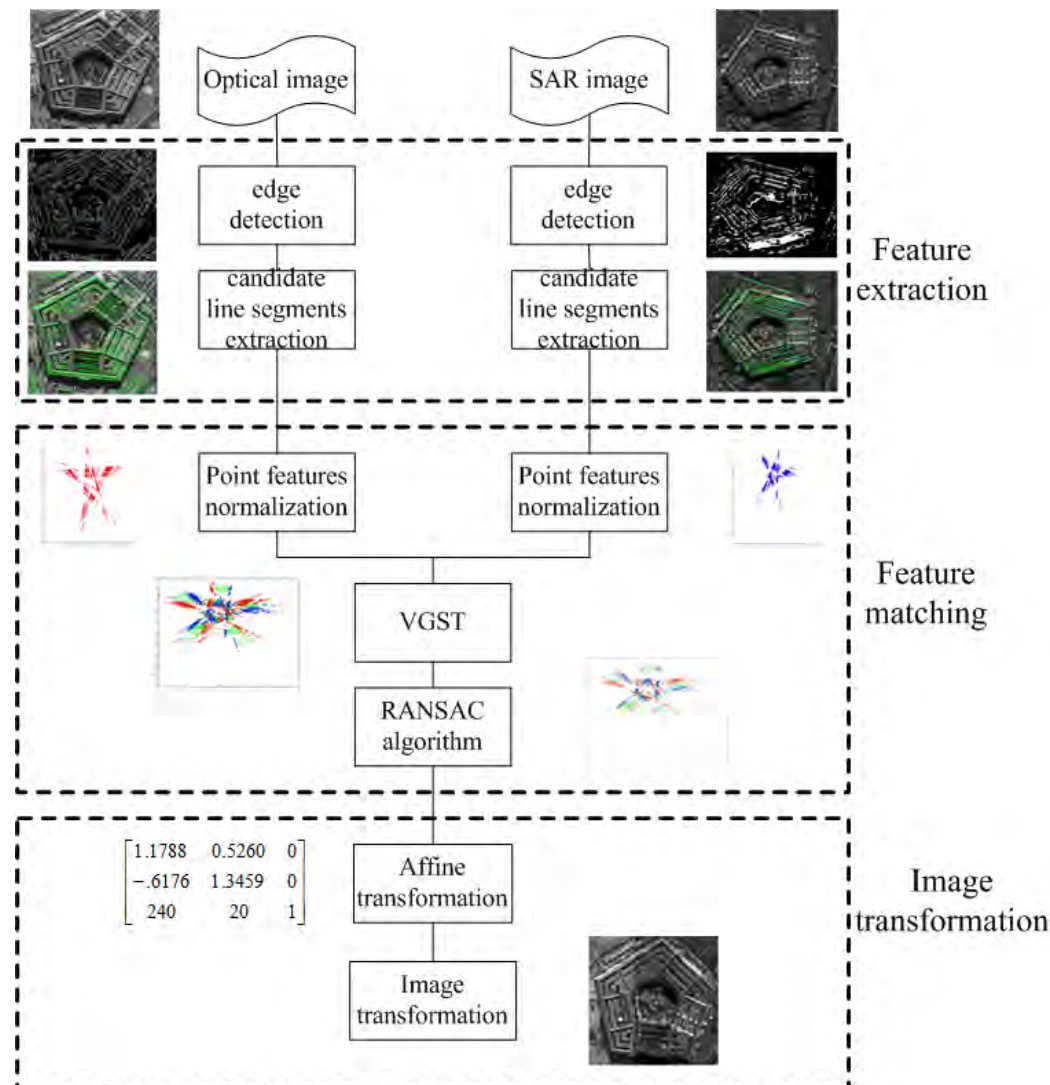
Geometric  
correction  
with control  
points



**Difficulties: Different side-looking and resolution**  
**Radiometric and geometric difference**  
**Strong speckle noises *etc.***



# An automatic optical and SAR image registration method based on VGST & line features



1) Most linear feature based methods use line segments or contours as matching primitive, however, we use line intersection as matching primitive so that conjugate line segment just needs to be collinear and several line segments can provide enough matching primitives.

2) As to matching point features, a new method called VGST is introduced to improve the poor performance of traditional spectral graph theory (GST) based methods in sensitivity to local optimization.



Optical image



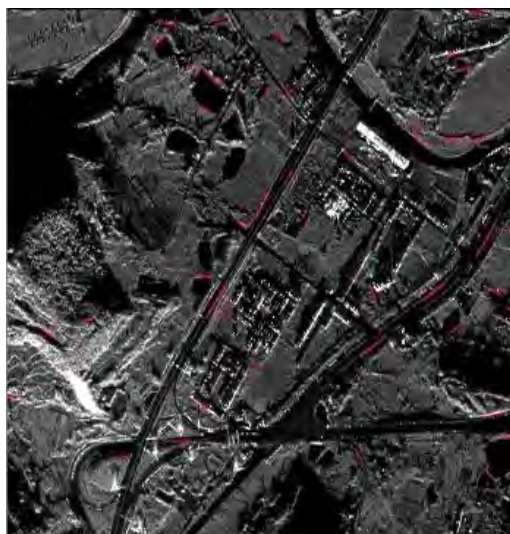
Line detection of optical image



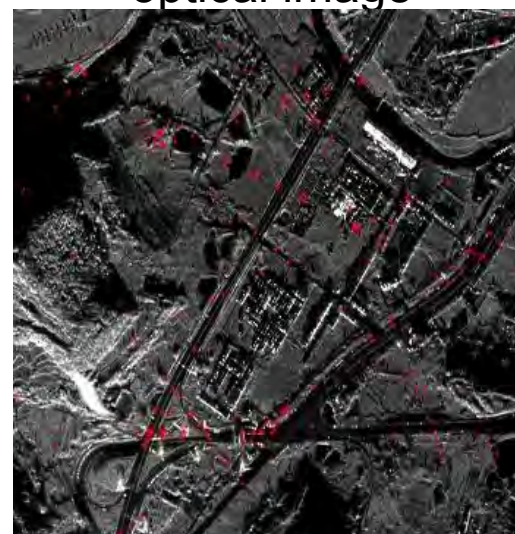
Line intersections of  
optical image



SAR image

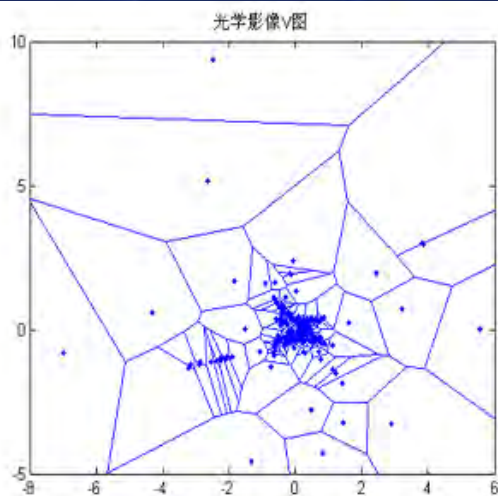


Line detection of SAR image

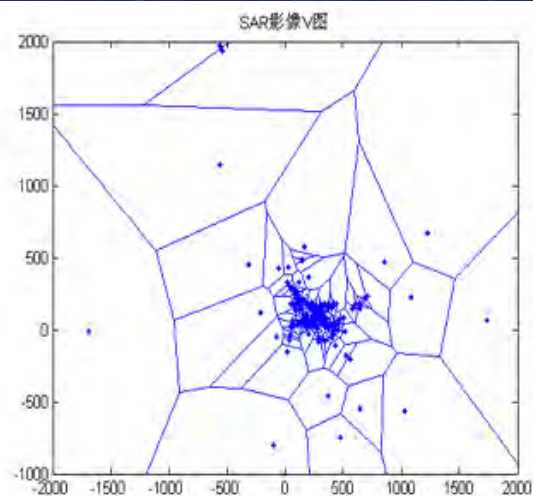


Line intersections of  
SAR image

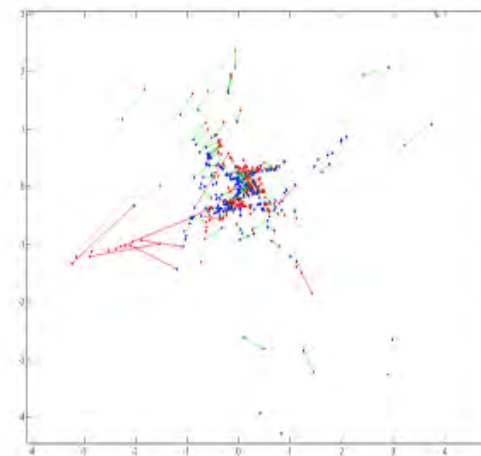




Voronoi diagram generated  
by points from optical image



Voronoi diagram generated  
by points from SAR image



Marching result of  
Voronoi diagram



Registration result using  
MIOI (Chen *et al.*, 2003)



Registration result using  
MIHT (Suri and Reinartz,  
2010)



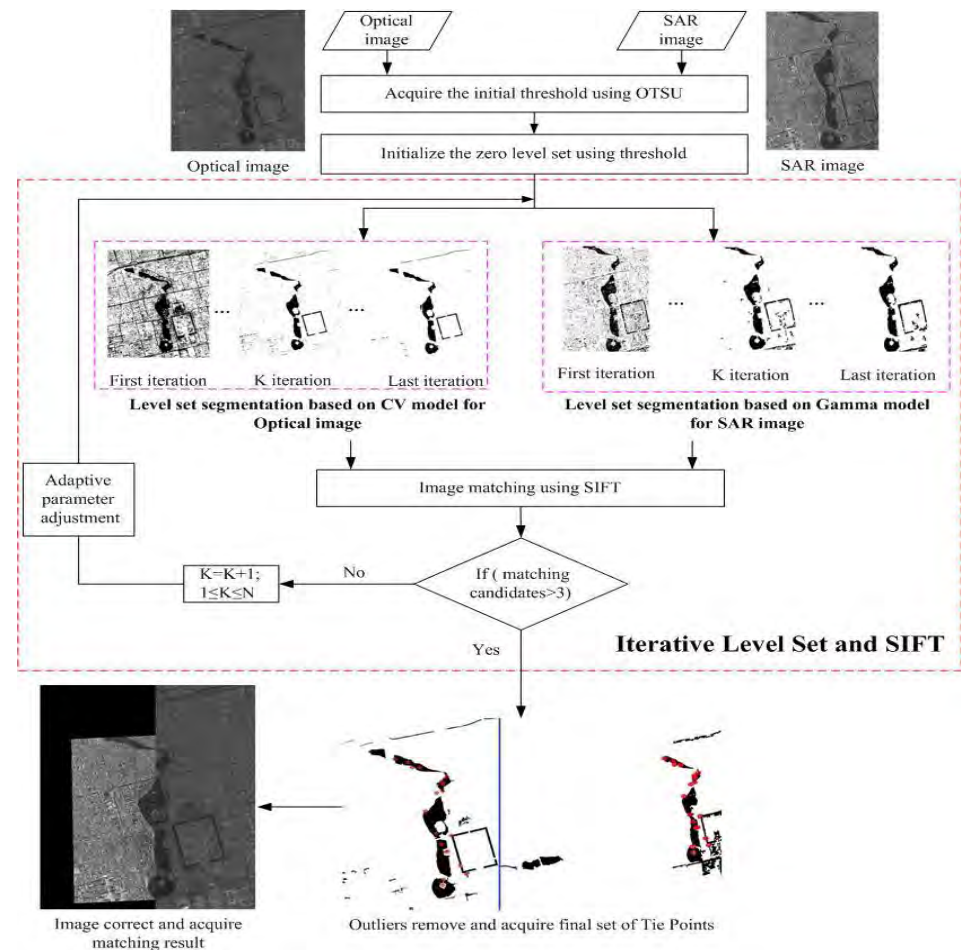
Registration result using  
liner features and  
Voronoi diagram



# A simultaneous image segmentation and registration method based on level set



- Traditionally, segmentation and registration have been solved as two independent problems. However, if we use segmentation result for registration the segmentation methods become very important
- No matter which segmentation method we use, it is almost impossible to obtain perfect registration result. So it is a good choice to integrate segmentation and registration simultaneously. And this is extremely important to real-time application



H. G. Sui, C. Xu, J. Y. Liu, K. M. Sun, C. F. Wen, 2012, "A novel multi-scale level set method for SAR image segmentation based on a statistical model" , *Int. J. Remote Sens.*, 33(17), pp.5600-5614.







# Example 3: Extraction of quake lake boundary using multi-temporal optical and SAR images

FW-2 (2 meter) (May,14,2008)

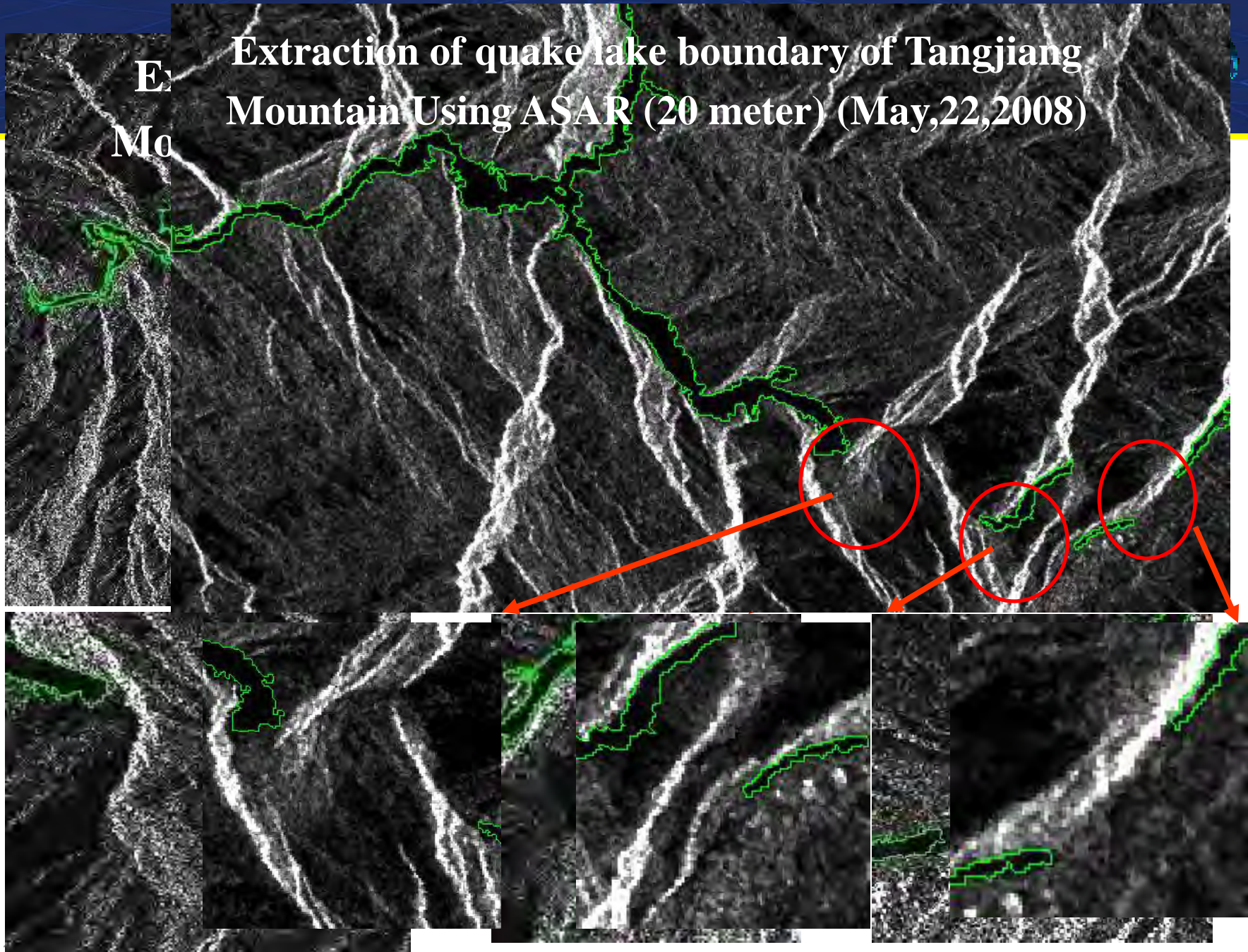
Extraction of quake lake boundary of Tangjiang Mountain  
using SPOT5 (10meters) (May,16,2008)

25-Oct



Ex  
Mo

# Extraction of quake lake boundary of Tangjiang Mountain Using ASAR (20 meter) (May,22,2008)



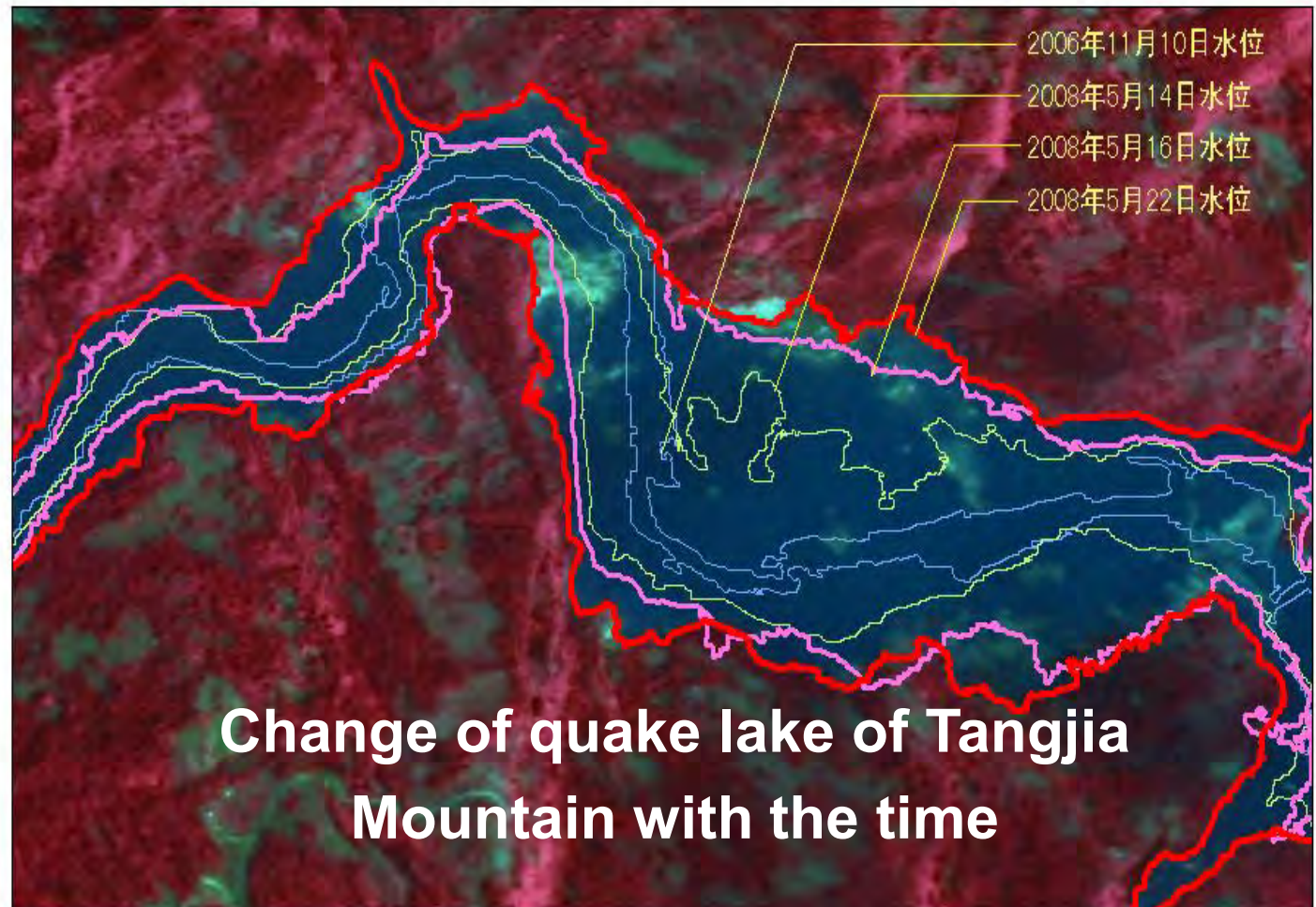


# Airborne Monitoring Tangjiashan Quake Lake

## Dam of Tangjiashan Quake Lake



北川唐家山堰塞湖水位涨势图



图例

- 2006年11月10日水位线
- 2008年5月14日水位线
- 2008年5月16日水位线
- 2008年5月22日水位线

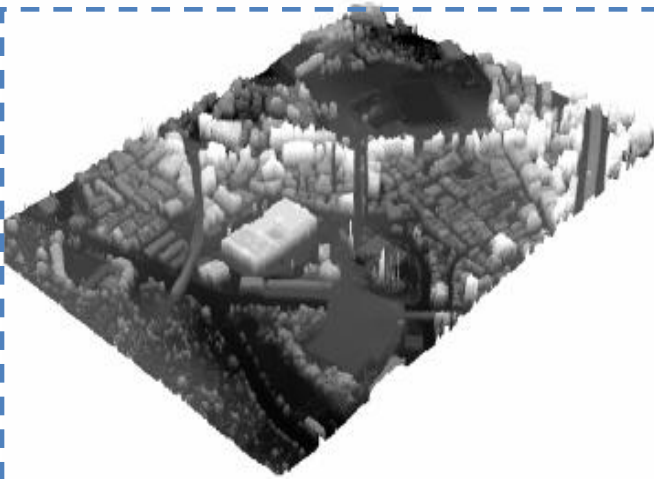
比例尺: 1:10000

制作时间: 2008年6月10日

制作单位: 武汉大学

25-Oct-13

# Example 4: 3D change detection using optical image and LIDAR data



**LIDAR data**



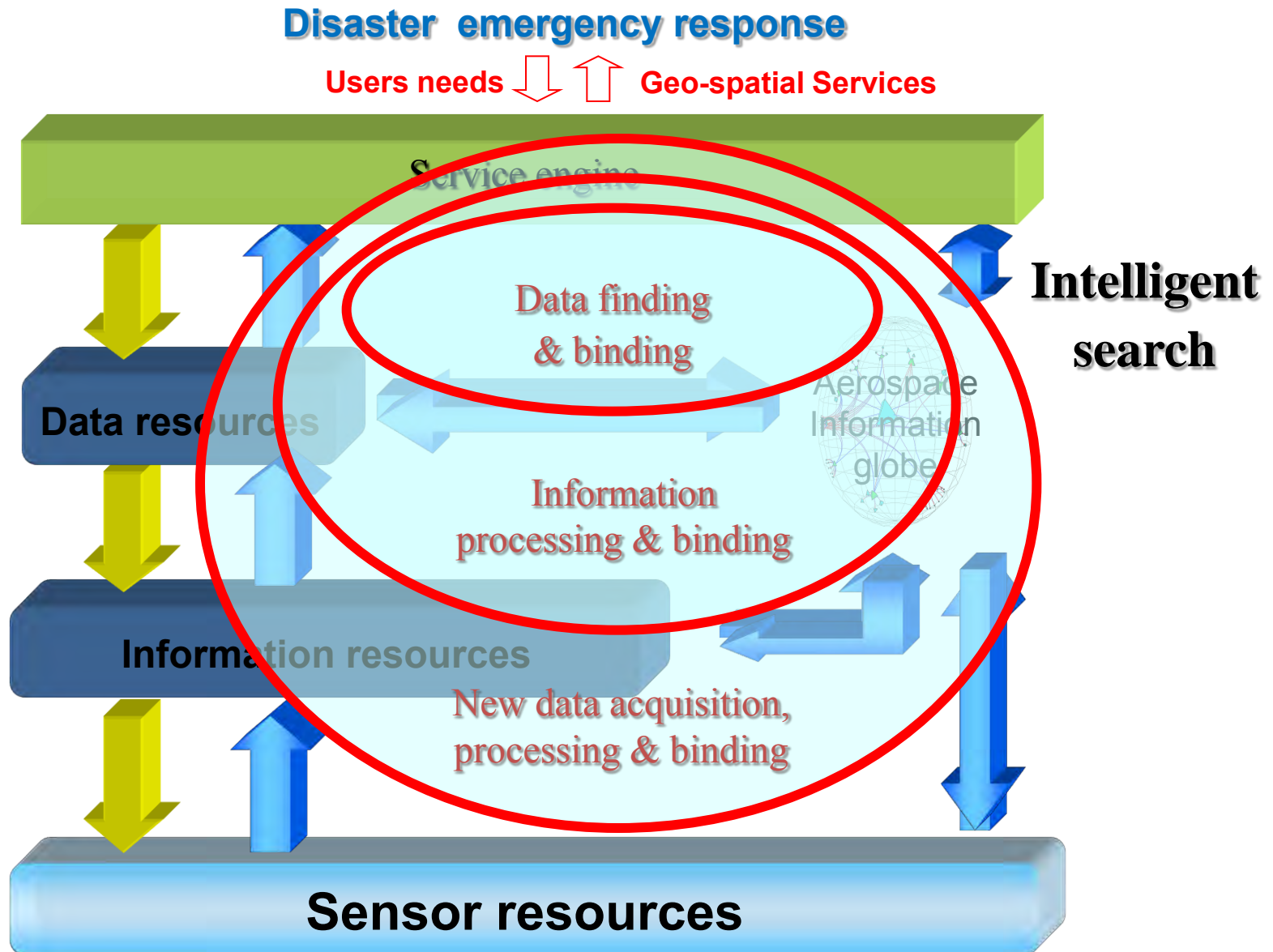
**New 3D model generated using UAV images**



**3D change detection result**



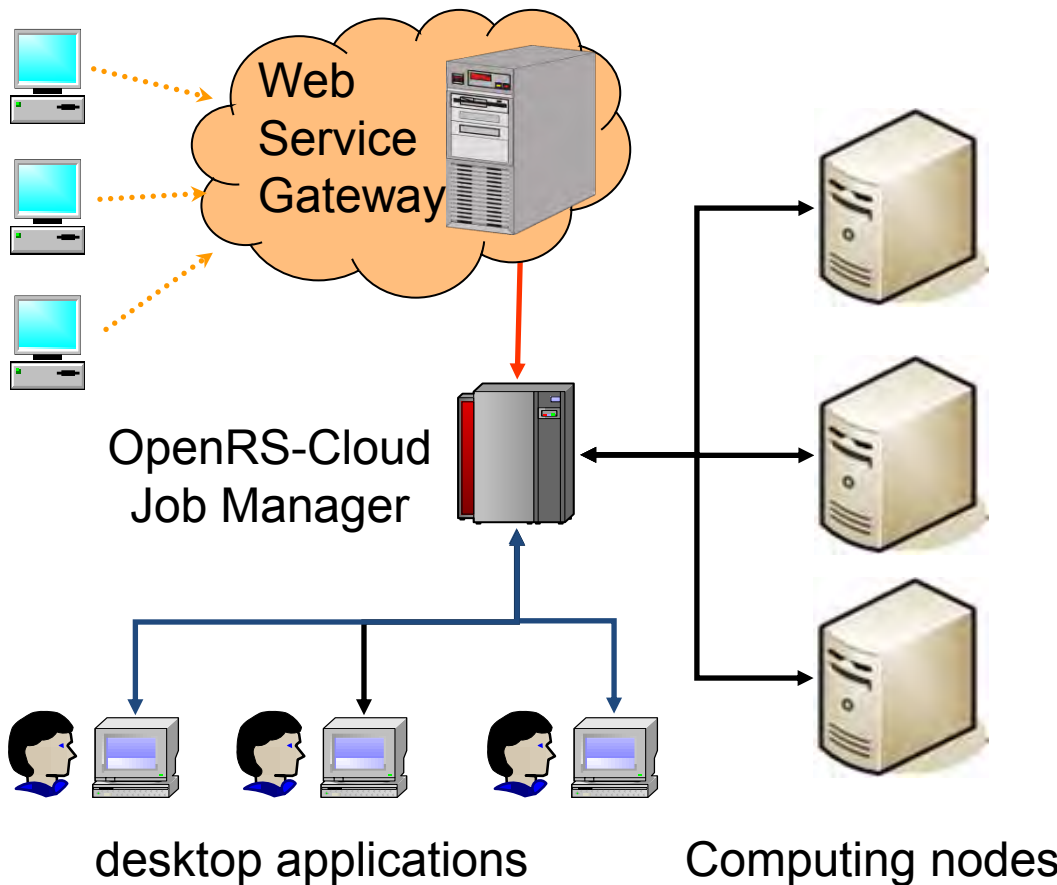
# Challenge 4: Online task-oriented service



# OpenRS: Remotely sensed cloud platform



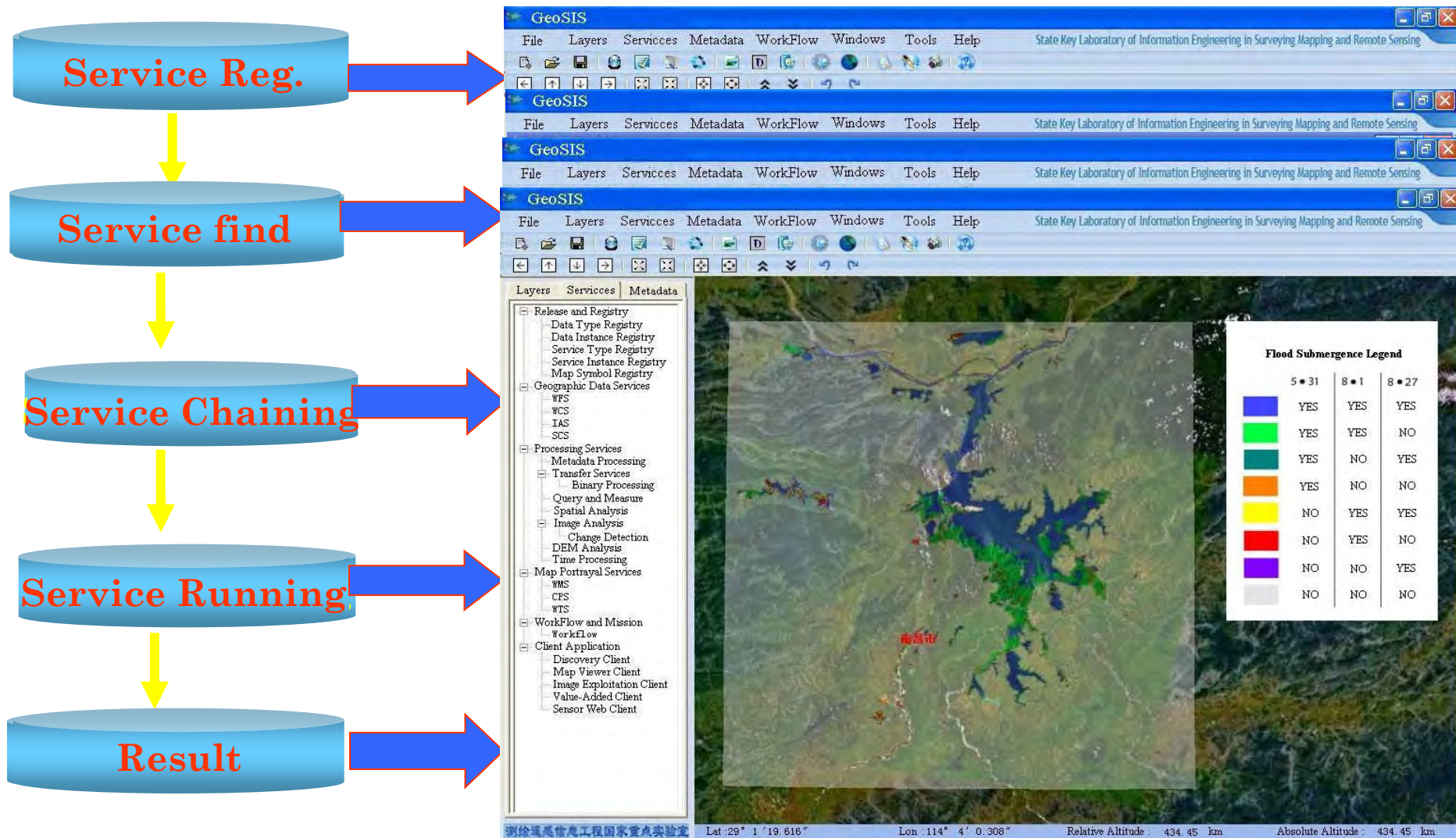
Web applications



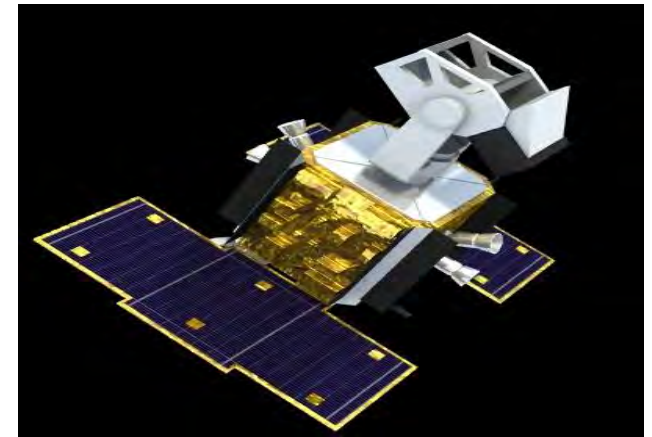
Provide opening architecture for desktop processing, distributed and parallel processing, network service processing.



# Example :Online flood disaster monitoring service



# Challenge 5: Onboard real-time processing



**Onboard processing are mainly concentrated in some data preprocessing algorithms, automatic advanced products generation and information extraction are still very difficult**



# 3、Conclusions



## 4R service

( At the right time and right place to deliver the right information to the right people )



## 5R real-time service

( At the right time and right place to real-time deliver the right information to the right people )

*“The world is changing very fast. Big will not beat small anymore. It will be the fast beating the slow.”*

— Rupert Murdoch

*“By 2012, 70% of Global. 1000 organizations will load detailed data into memory as the primary method to optimize BI application performance.”*

- Gartner

**Thank you !**  
**Welcome to Wuhan University!**

